



# CST207

## DESIGN AND ANALYSIS OF ALGORITHMS

Lecture 8: Backtracking

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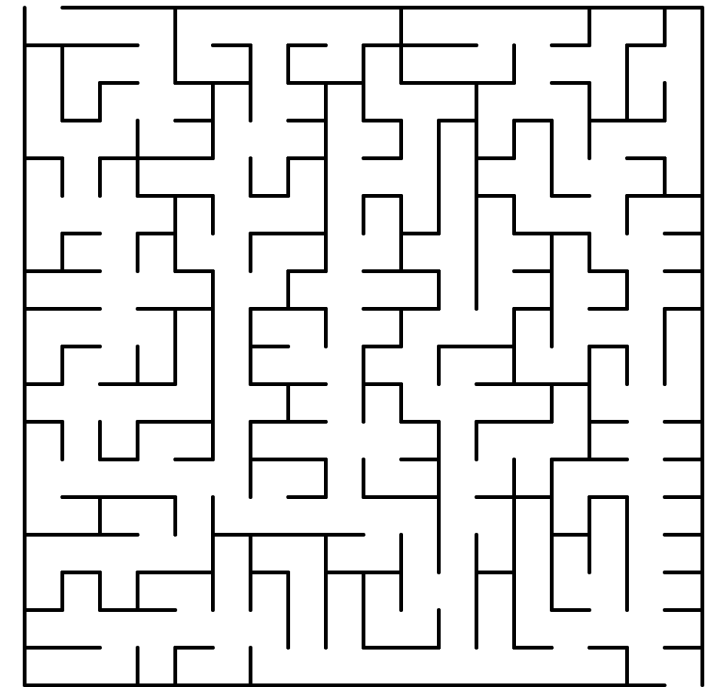
Office hour: 2pm-4pm Mon & Thur

# Outlines

- $n$ -Queens Problem
- The Sum-of-Subsets Problem
- Graph Coloring
- The Hamiltonian Circuits Problem
- The 0-1 Knapsack Problem

# Backtracking

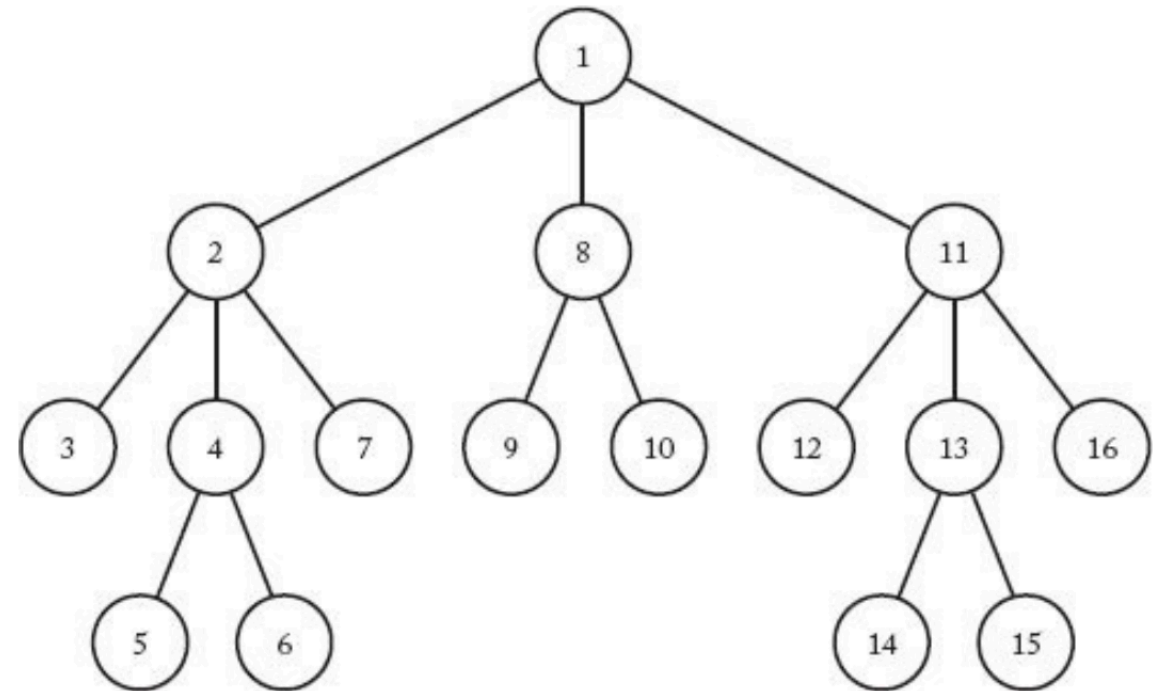
- A simple and straightforward strategy to escape from a maze is:
  - Go as deep as possible until reach a dead end.
  - Go back to the last fork and choose another path.
- If we have a sign at the fork to show dead ends, we can avoid that path.
  - This is backtracking.
- Backtracking is used to solve problems in which a *sequence* of objects is chosen from a specified *set* so that the sequence satisfies some *criterion*.



A maze

# Depth-First Search

- A *preorder* tree traversal is a *depth-first search (DFS)* of the tree.
  - The root is visited first, and a visit to a node is followed immediately by visits to all descendants of the node.
- Backtracking is a modified depth-first search of a tree.

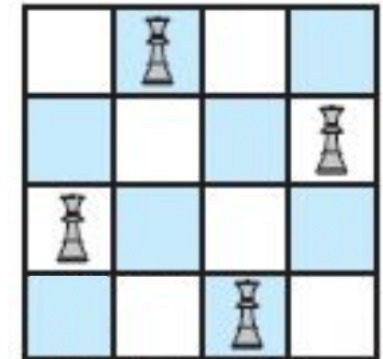




# $n$ -QUEENS PROBLEM

# $n$ -Queens Problem

- The goal in this problem is to position  $n$  queens on an  $n \times n$  chessboard so that no two queens threaten each other.
  - No two queens may be in the same row, column, or diagonal.
- The *sequence* in this problem is the  $n$  positions in which the queens are placed.
- The *set* for each choice is the  $n^2$  possible positions on the chessboard.
- The *criterion* is that no two queens can threaten each other.
- The  $n$ -Queens problem is a generalization of its instance when  $n = 8$ , which is the instance using a standard chessboard.
  - For the sake of brevity, we will illustrate backtracking using the instance when  $n = 4$ .

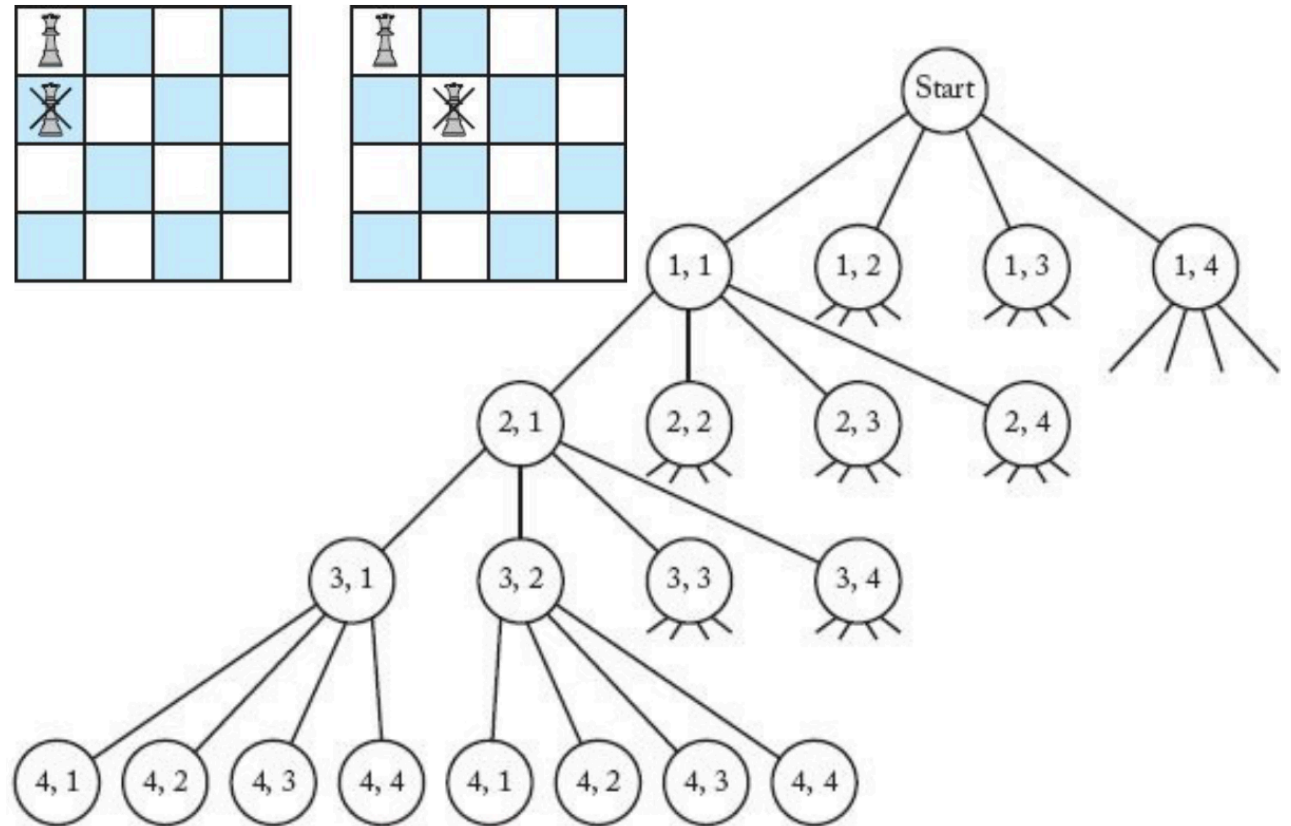


# $n$ -Queens Problem

- Our task is to position four queens on a  $4 \times 4$  chessboard so that no two queens threaten each other.
- We can immediately simplify matters by realizing that **no two queens can be in the same row.**
- The instance can then be solved by assigning each queen a different row and checking which column combinations yield solutions.
  - There are  $4 \times 4 \times 4 \times 4 = 256$  candidate solutions.

# $n$ -Queens Problem

- We can create the candidate solutions by constructing a *state space tree*.
- A path from the root to a leaf is a candidate solution.
- Actually, we don't need to check every leaf.
  - We may early stop if we find out that this path definitely leads to a dead end.





# Promising Function

- *Backtracking* is the procedure whereby, after determining that a node can lead to nothing but dead ends, we go back (“backtrack”) to the node’s parent and proceed with the search on the next child.
- We call a node *nonpromising* if when visiting the node we determine that it cannot possibly lead to a solution. Otherwise, we call it *promising*.
- The promising checking is done with DFS.
- This process called *pruning* the state space tree, and the subtree consisting of the visited nodes is called the *pruned state space tree*.

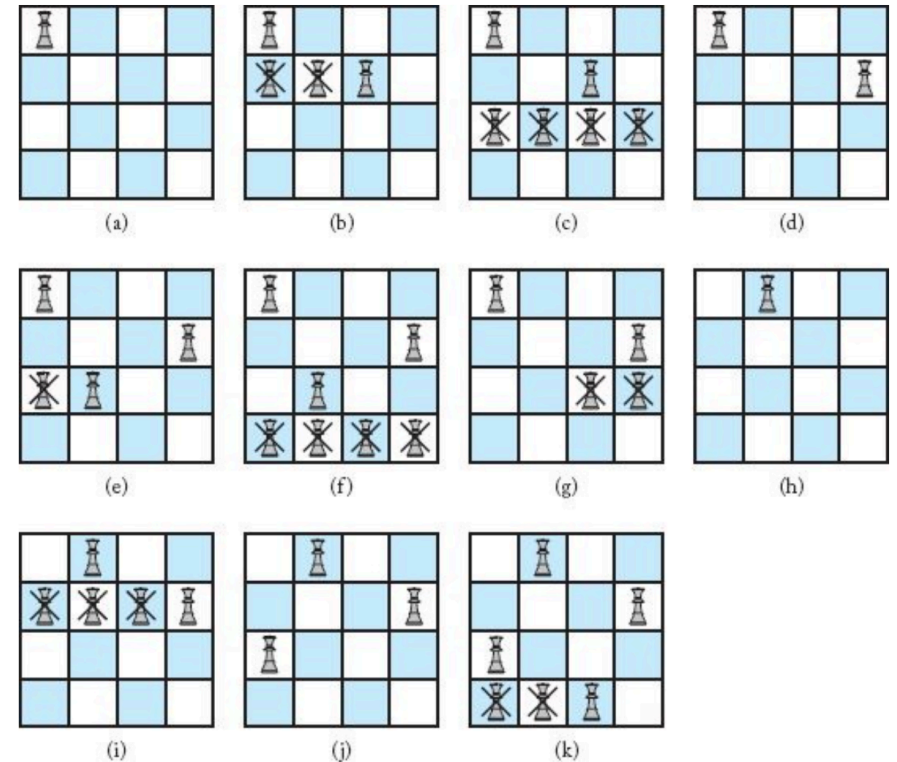
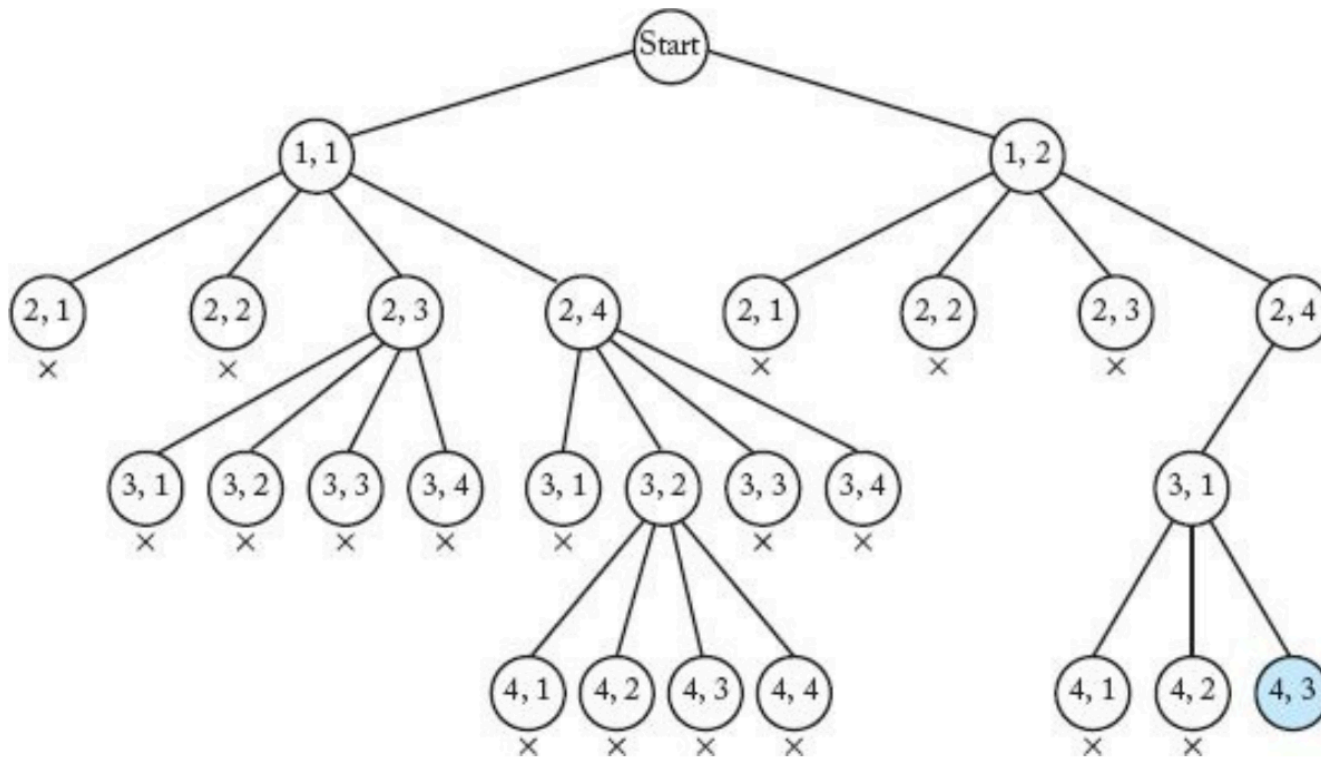
# Promising Function

- The root of the state space tree is passed to `checknode` at the top level.
- A visit to a node consists of first checking whether it is promising.
  - If it is promising and there is a solution at the node, the solution is printed.
  - If there is not a solution at a promising node, the children of the node are visited.
- We call it the *promising function* for the algorithm, which is different in each application of backtracking.
- A backtracking algorithm is same as DFS, except that the children of a node are visited only when the node is promising and there is not a solution at the node.

```
void checknode (node v)
{
    node u;

    if (promising(v))
        if (there is a solution at v)
            write the solution
        else
            for (each child u of v)
                checknode(u);
}
```

# Backtracking of $n$ -Queens Problem



The backtracking algorithm only checks 27 nodes, while DFS checks 155 nodes before finding that same solution.

# Backtracking

- Notice that a backtracking algorithm **does not need to actually create a tree**.
  - Usually, they are implemented by recursion (thus a stack).
- Rather, it only needs to keep track of the values in the current branch being investigated.
- The state space tree exists **implicitly** in the algorithm because it is not actually constructed.

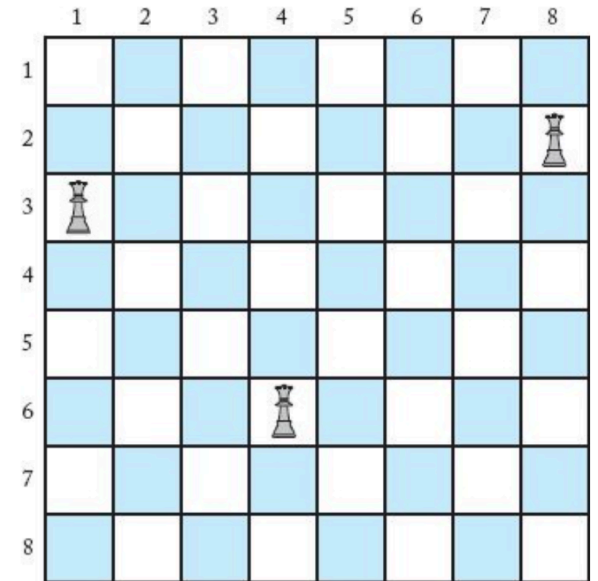
# $n$ -Queens Problem

- For each row, we put one queen. Thus, the promising function only needs to check if two queens are in the same column or diagonal.
- Let  $col(i)$  be the column where the queen in the  $i$ th row is located.
- Condition that two queens are in the same column:

$$col(i) = col(k).$$

- Condition that two queens are in the same diagonal :

$$col(i) - col(k) = i - k \quad \text{or} \quad col(i) - col(k) = k - i.$$



# Pseudocode of $n$ -Queens Problem

- As usual, non-changing variables  $n$  and  $col$  are not inputs to the recursive function. They are defined globally.
- The top level call is `queens(0)`.
- For the terminate condition  $i == n$ , the program doesn't stop, until all solutions are found.

```
void queens (index i)
{
    index j;

    if (promising(i))
        if (i == n)
            cout << col[1] through col[n];
        else
            for (j = 1; j <= n; j++){
                col[i + 1] = j;
                queens(i + 1);
            }
}
```

```
bool promising (index i)
{
    index k;
    bool flag;

    k = 1;
    flag = true;
    while (k < i && flag){ // only deal with previous i rows
        if (col[i] == col[k] || abs(col[i] - col[k]) == i - k)
            flag = false;
        k++;
    }
    return flag;
}
```

# Analysis of $n$ -Queens Problem

- For DFS, the tree contains 1 node at level 0,  $n$  nodes at level 1,  $n^2$  nodes at level 2, ... , and  $n^n$  nodes at level  $n$ . The total number of nodes is

$$1 + n + n^2 + n^3 + \dots + n^n = \frac{n^{n+1} - 1}{n - 1}.$$

- For backtracking, if we only check the column, the upper bound of promising nodes are

$$1 + n + n(n - 1) + n(n - 1)(n - 2) + \dots + n!.$$

- For  $n = 8$ , DFS has 19,173,961 nodes while backtracking only has at most 109,601 promising nodes.
- Thus, the purpose of backtracking is to use promising function to improve DFS as much as possible.
  - Save time by stop earlier.



# THE SUM-OF-SUBSETS PROBLEM



# The Sum-of-Subsets Problem

- In the Sum-of-Subsets problem, there are  $n$  positive integers (weights)  $w_i$  and a positive integer  $W$ .
  - Similar to 0-1 Knapsack problem but without value.
- The goal is to find all subsets of the integers that sum to  $W$ .

- Example:

- Suppose that  $n = 5$ ,  $W = 21$ , and

$$w_1 = 5, w_2 = 6, w_3 = 10, w_4 = 11, w_5 = 16.$$

- The solutions is  $\{w_1, w_2, w_3\}$ ,  $\{w_1, w_5\}$  and  $\{w_3, w_4\}$  because

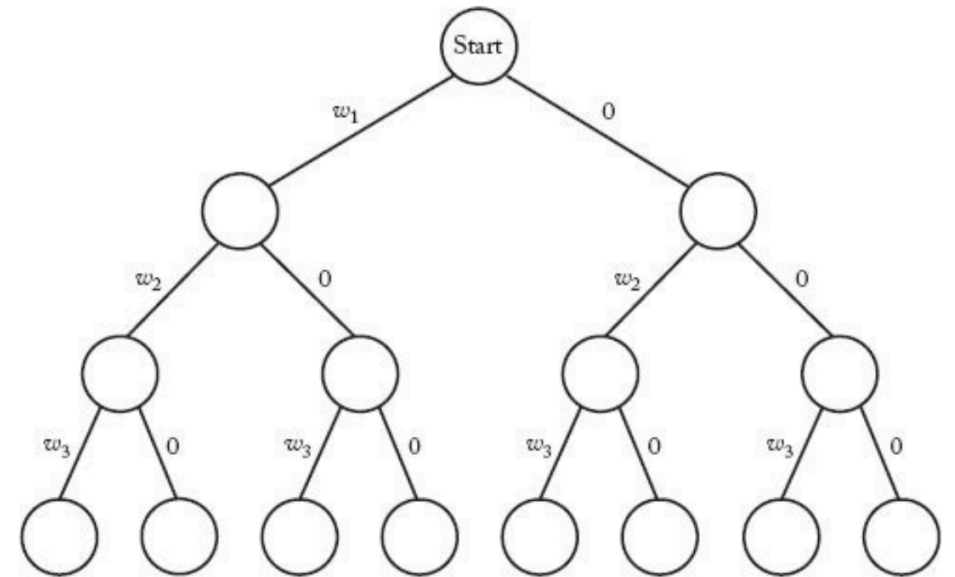
$$w_1 + w_2 + w_3 = 5 + 6 + 10 = 21,$$

$$w_1 + w_5 = 5 + 16 = 21,$$

$$w_3 + w_4 = 10 + 11 = 21.$$

# The Sum-of-Subsets Problem

- One approach is to create a state space tree.
- Each subset is represented by a path from the root to a leaf.
  - We go to the left from the root to include  $w_1$ , and we go to the right to exclude  $w_1$ .
  - We go to the left from a node at level 1 to include  $w_2$ , and we go to the right to exclude  $w_2$ .
  - ...
- When we include  $w_i$ , we write  $w_i$  on the edge where we include it. When we do not include  $w_i$ , we write 0.



# Promising Function

- If we sort the weights in nondecreasing order before doing the search, there is an obvious sign telling us that a node is nonpromising.
- Let *weight* to be the sum of the weights that have been included up, and *remain* is the sum of the weight that is remained to be checked.
- There are two cases that a node at the *i*th level is nonpromising:
  - Case 1: Including  $w_{i+1}$  exceeds  $W$ :

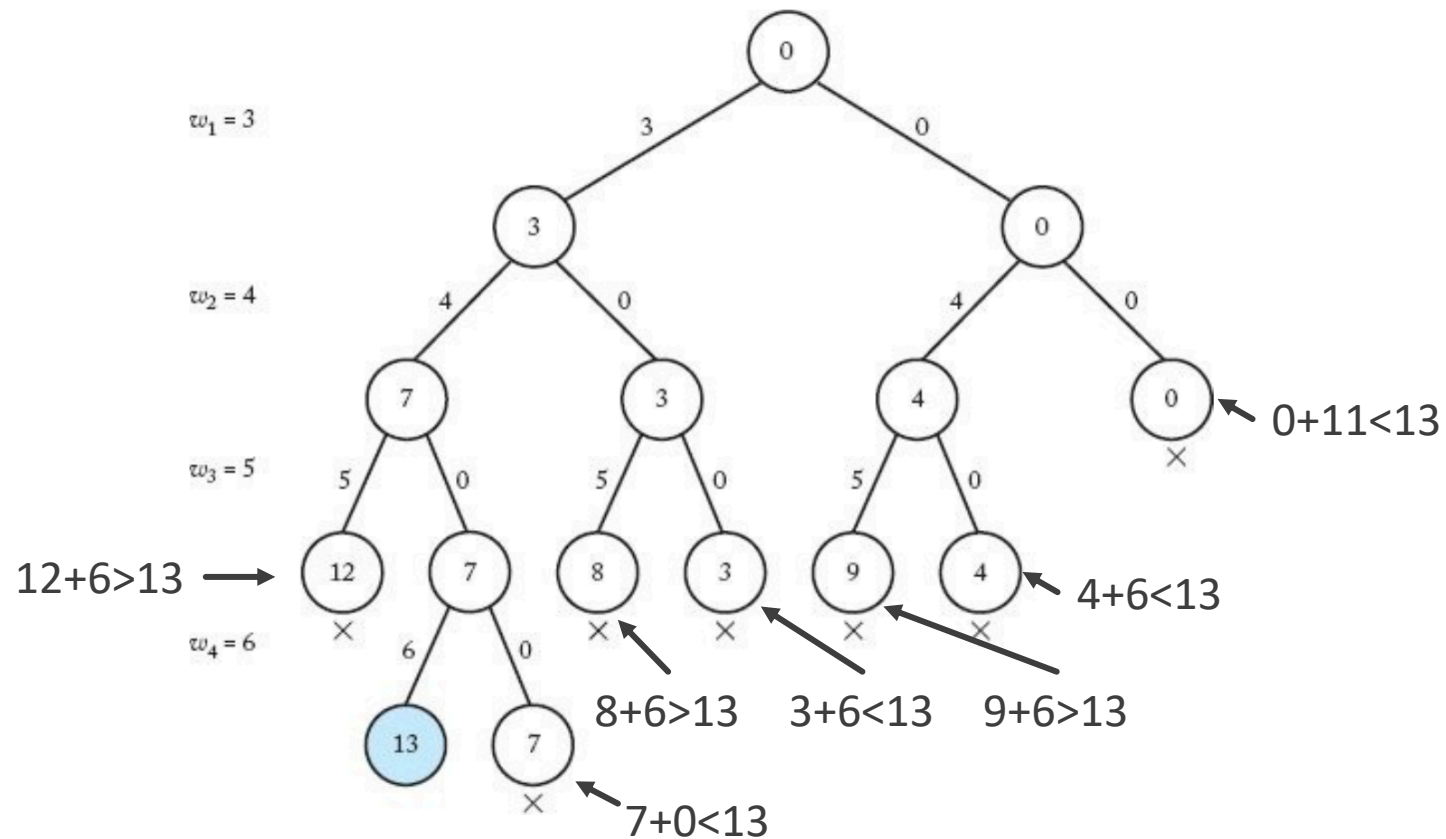
$$weight + w_{i+1} > W.$$

- Case 2: Including all the remaining can't reach  $W$ :

$$weight + remain < W.$$

# Example

$n = 4, W = 13$



# Pseudocode

- `n`, `w`, `W` and `include` are defined globally.

- The top-level call is

`sum_of_subsets(0, 0, remain)`

where `remain` is initialized as:

$$remain = \sum_{j=1}^n w[j].$$

- Actually, we don't need to test if `i==n`, because it has been tested by `weight+remain>=W` in function `promising`.
  - When `i==n`, `remain` must be 0.

```
void sum_of_subsets (index i, int weight, int remain)
{
    if (promising(i))
        if (weight == W)
            cout << include[1] through include[i];
        else{
            include[i + 1] = "yes";
            sum_of_subsets(i + 1, weight + w[i + 1], remain - w[i + 1]);
            include[i + 1] = "no";
            sum_of_subsets(i + 1, weight, remain - w[i + 1]);
        }
}

bool promising (index i);
{
    return (weight + remain >= W) && (weight == W || weight + w[i + 1] <= W);
}
```

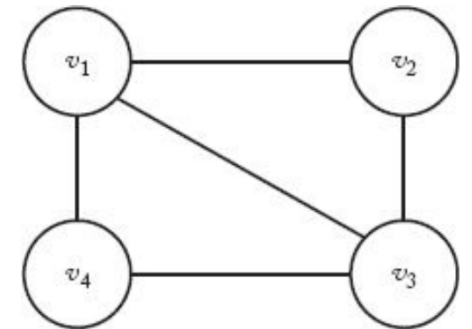


# GRAPH COLORING

# Graph Coloring

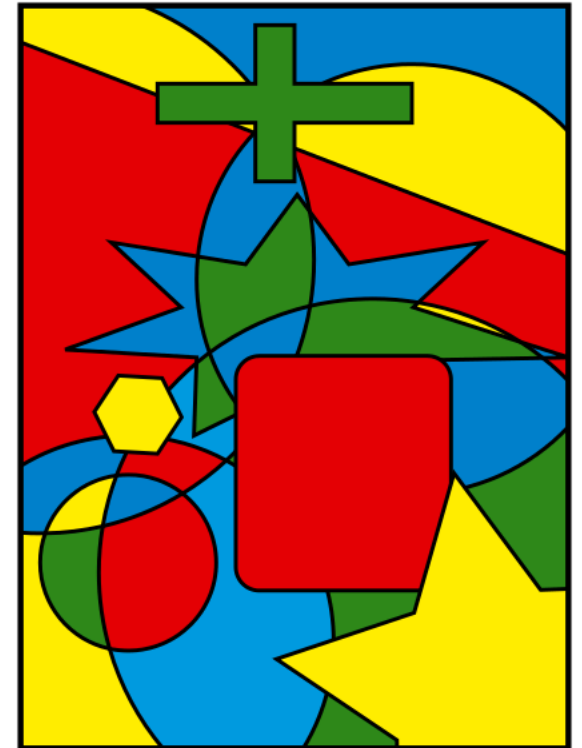
- The  $m$ -Coloring problem concerns finding all ways to color an undirected graph using at most  $m$  different colors, so that no two adjacent vertices are the same color.
- There is no solution to the 2-Coloring problem for this example graph.
- One solution to the 3-Coloring problem for this graph is as follows:

$v_1$  color 1  
 $v_2$  color 2  
 $v_3$  color 3  
 $v_4$  color 2



# Graph Coloring

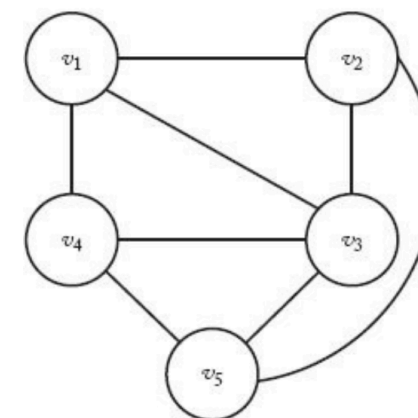
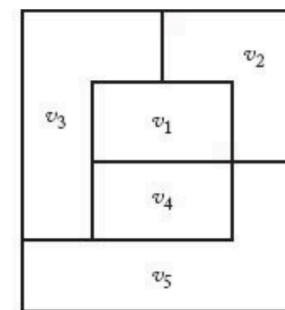
- An important application of graph coloring is the coloring of maps.
- In mathematics, a very famous problem is called the **four color theorem**.
  - It has been proved with a computer software in 1976.
- Given any separation of a plane into contiguous regions, producing a figure called a map, no more than four colors are required to color the regions of the map so that no two adjacent regions have the same color.





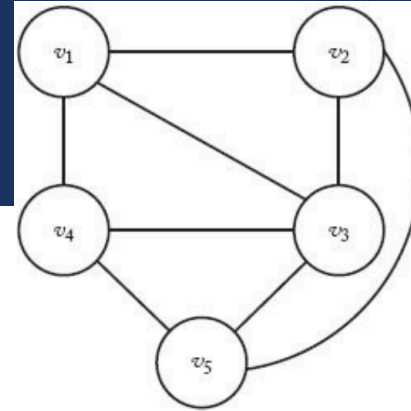
# Graph Coloring

- A graph is called *planar* if it can be drawn in a plane in such a way that no two edges cross each other.
  - However, if we were to add the edges  $(v_1, v_5)$  and  $(v_2, v_4)$  it would no longer be planar.
- To every map there corresponds a planar graph.
- The  $m$ -Coloring problem for planar graphs is to determine how many ways the map can be colored, using at most  $m$  colors, so that no two adjacent regions are the same color.

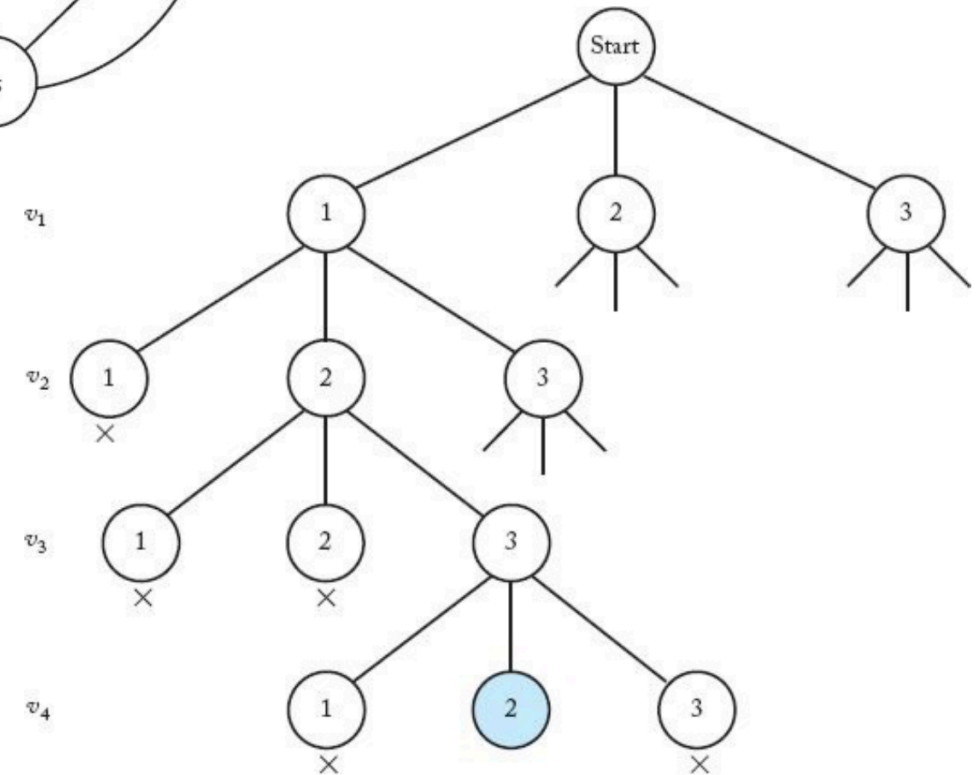


A planar graph

# Graph Coloring



- A straightforward state space tree is:
  - Each possible color is tried for vertex  $v_1$  at level 1;
  - Each possible color is tried for vertex  $v_2$  at level 2;
  - ...
  - Until each possible color has been tried for vertex  $v_n$  at level  $n$ .
- Each path from the root to a leaf is a candidate solution.
- We can backtrack in this problem because a node is nonpromising if a two adjacent vertices are colored by the same color.



# Pseudocode of Graph Coloring

- The top level call is `m_coloring(0)`.
- The pseudocode is exactly same as the  $n$ -Queens problem, except the if-condition in promising function.

```
void m_coloring (index i)
{
    int color;

    if (promising(i))
        if (i == n)
            cout << vcolor[1] through vcolor[n];
        else
            for (color = 1; color <= m; color++){
                vcolor[i + 1] = color;
                m_coloring(i + 1);
            }
}
```

```
bool promising (index i)
{
    index j;
    bool flag;

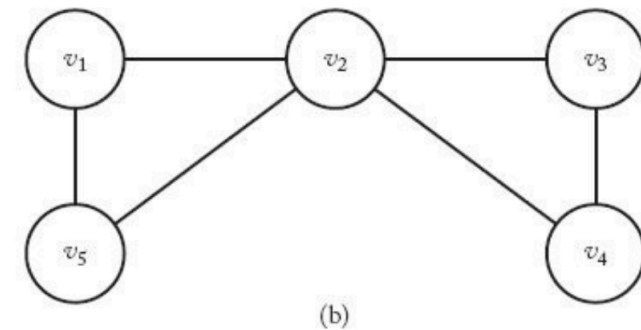
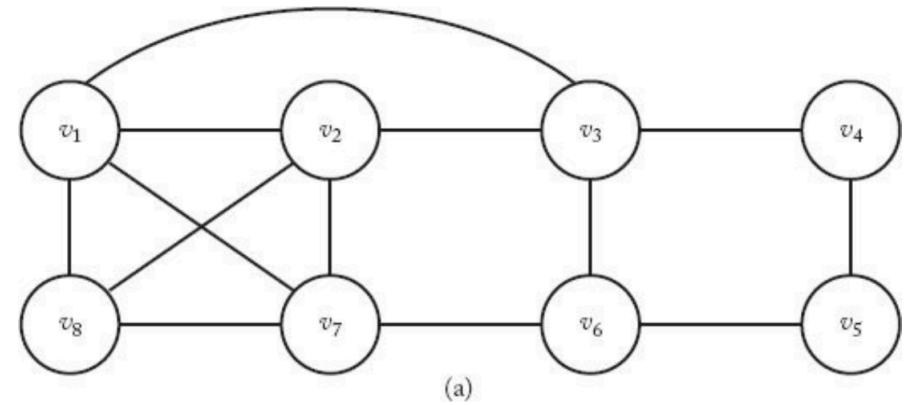
    flag = true;
    j = 1;
    while (j < i && flag){
        if (W[i][j] && vcolor[i] == vcolor[j])
            flag = false;
        j++;
    }
    return flag;
}
```



# THE HAMILTONIAN CIRCUITS PROBLEM

# The Hamiltonian Circuits Problem

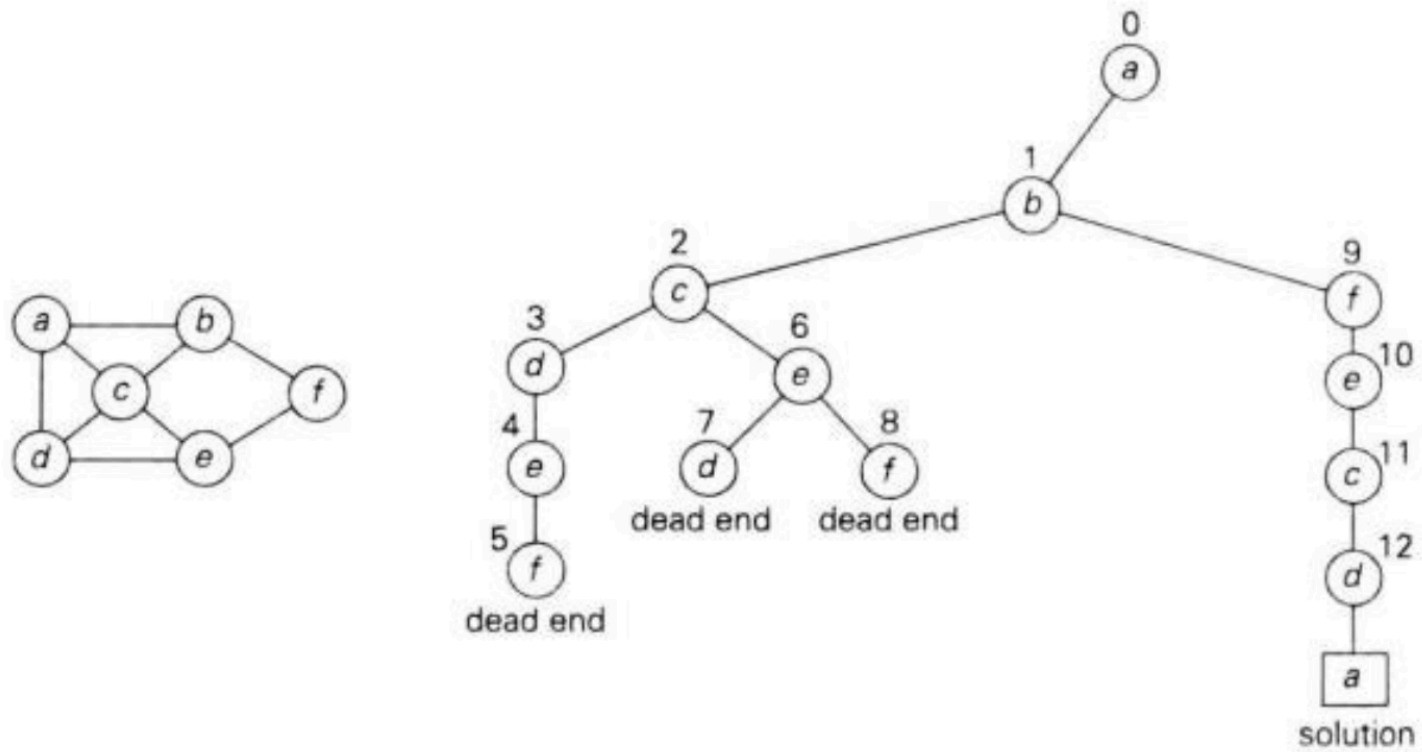
- Given a connected, undirected graph, a *Hamiltonian Circuit* (also called a tour) is a path that starts at a given vertex, visits each vertex in the graph exactly once, and ends at the starting vertex.
- The graph in Figure (a) contains the Hamiltonian Circuit  $[v_1, v_2, v_8, v_7, v_6, v_5, v_4, v_3, v_1]$ , but the one in Figure (b) does not contain a Hamiltonian Circuit.



# The Hamiltonian Circuits Problem

- A state space tree for this problem is as follows.
  - Put the starting vertex at level 0 in the tree; call it the zeroth vertex on the path.
  - At level 1, consider each vertex other than the starting vertex as the first vertex.
  - At level 2, consider each of these same vertices as the second vertex, and so on.
  - Finally, at level  $n - 1$ , consider each of these same vertices as the  $(n - 1)$ st vertex.
- Consider backtrack in this state space tree:
  - The  $i$ th vertex on the path must be adjacent to the  $(i - 1)$ st vertex on the path.
  - The  $(n - 1)$ st vertex must be adjacent to the 0th vertex (the starting one).
  - The  $i$ th vertex cannot be one of the first  $i - 1$  vertices.

# The Hamiltonian Circuits Problem



# Pseudocode of the Hamiltonian Circuits Problem

- The top-level call is:  
vindex[0]=1;  
hamiltonian(0);

```
void hamiltonian (index i)
{
    index j;

    if (promising(i))
        if (i == n - 1)
            cout << vindex[0] through vindex[n - 1];
        else
            for (j = 2; j <= n; j++){
                vindex[i + 1] = j;
                hamiltonian(i + 1);
            }
}
```

```
bool promising (index i)
{
    index j;
    bool flag;

    if (i == n - 1 && !W[vindex[n - 1]][vindex[0]])
        flag = false;
    else if (i > 0 && !W[vindex[i - 1]][vindex[i]])
        flag = false;
    else{
        flag = true;
        j = 1;
        while (j < i && flag){
            if (vindex[i] == vindex[j])
                flag = false;
            j++;
        }
    }
    return flag;
}
```





# THE 0-1 KNAPSACK PROBLEM

# Knapsack Problem Recall

- Problem description:
  - Given  $n$  items and a "knapsack."
  - Item  $i$  has weight  $w_i > 0$  and has value  $v_i > 0$ .
  - Knapsack has capacity of  $W$ .
  - Goal: Fill knapsack so as to maximize total value.
- Mathematical description:
  - Given two  $n$ -tuples of positive numbers  $\langle v_1, v_2, \dots, v_n \rangle$  and  $\langle w_1, w_2, \dots, w_n \rangle$ , and  $W > 0$ , we wish to determine the subset  $T \subseteq \{1, 2, \dots, n\}$  that

$$\text{maximize } \sum_{i \in T} v_i \quad \text{subject to } \sum_{i \in T} w_i \leq W$$

- Can backtracking solve this problem?

# The 0-1 Knapsack Problem

- We can solve this problem using a state space tree exactly like the one in the Sum-of-Subsets problem.
  - We go to the left from the root to include the first item, and we go to the right to exclude it.
  - We go to the left from a node at level 1 to include the second item, and we go to the right to exclude it.
  - ...
  - Each path from the root to a leaf is a candidate solution.

# The 0-1 Knapsack Problem

- This problem is different from the others discussed in this chapter in that it is *an optimization problem*.
  - It finds the maximum value, rather than a solution satisfying some conditions.
- We do not know if a node contains a solution until the search is over.
- If the items included up to a node have a greater total profit than the best solution so far, we change the value of the best solution so far.
  - However, we may still find a better solution at one of the node's descendants (by including more items).
  - Therefore, for optimization problems we always visit a promising node's children.

# Promising Function

- Similar to the sum-of-subsets problem, there are two cases that a node is nonpromising:
  - Case 1: Weights of included items exceeds  $W$ :  $weight \geq W$ .
    - $weight = W$  is also nonpromising because it may not be a solution and it cannot expand to its children.
  - Case 2: Even including all the remaining possible items can't exceed the existing best profit.

# Promising Function

- For the second case, we should calculate the profit bound of including all remaining possible items.
  - We use the idea of fractional knapsack with greedy approach, because it can bring us the upper bound.
  - We first sort the items in nonincreasing order according to the values of  $v_i/w_i$ .
  - The profit bound is calculated by fill the knapsack with fractional items in this order.
- For example,  $n = 4, W = 16$ :
  - If we don't include any item yet, the profit bound is
$$40 + 30 + (16 - 2 - 5) \times 5 = 115.$$
  - If now we include item 1 and don't include item 2, the profit bound is
$$40 + 50 + (16 - 2 - 10) \times 2 = 98.$$

$i$	$v_i$	$w_i$	$v_i/w_i$
1	\$40	2kg	20\$/kg
2	\$30	5kg	6\$/kg
3	\$50	10kg	5\$/kg
4	\$10	5kg	2\$/kg

# Promising Function

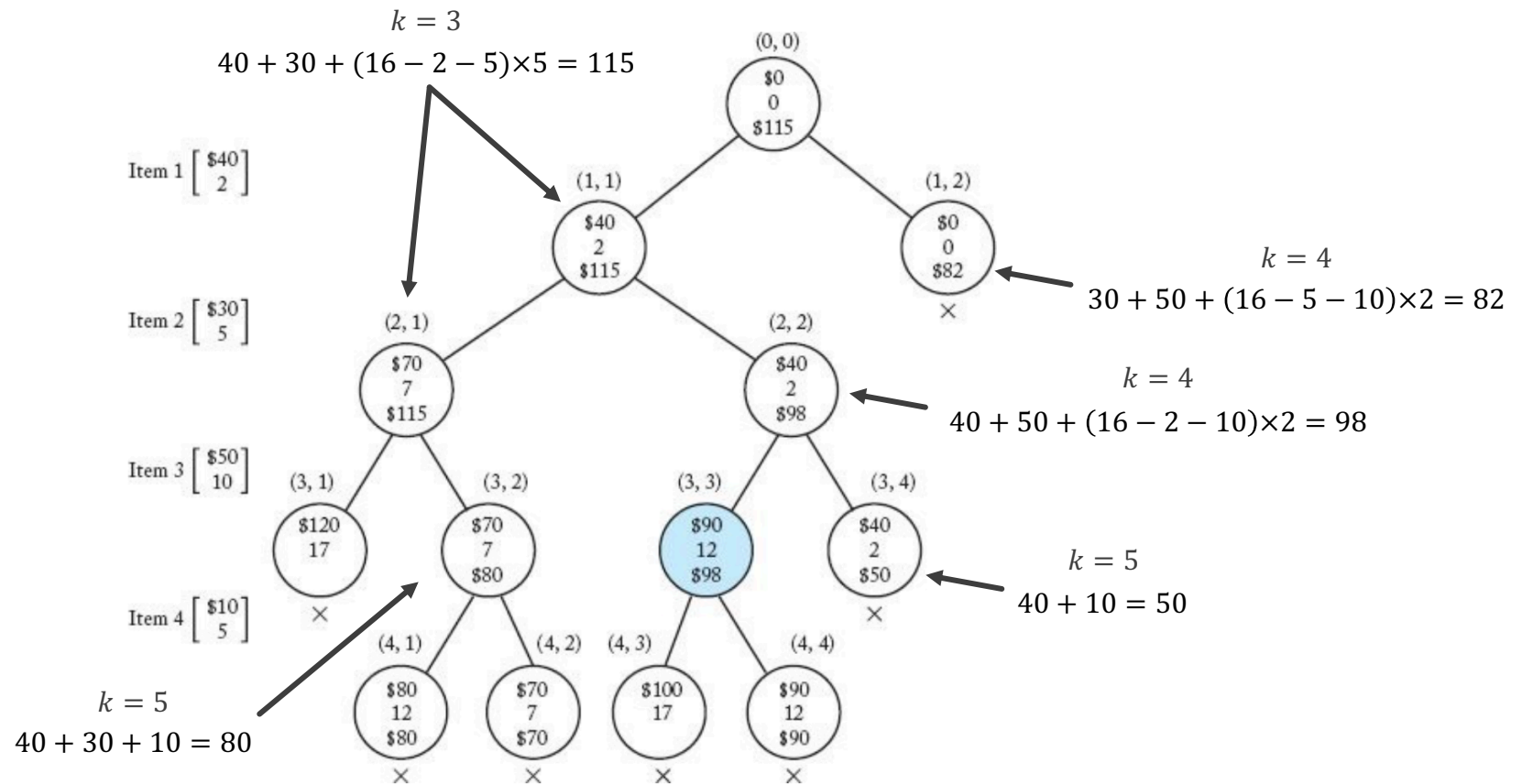
- Suppose the node is at level  $i$ , we first calculate  $k$  such that the level  $k$  is the one that would bring the sum of the weights *exceeds*  $W$ .
- Then we have:

$$\begin{aligned} \text{totweight} &= \text{weight} + \sum_{j=i+1}^{k-1} w_j, \\ \text{bound} &= \underbrace{\text{profit} + \sum_{j=i+1}^{k-1} v_j}_{\text{Profit from first } k-1 \text{ items taken}} + \underbrace{(W - \text{totweight})}_{\text{Capacity available for } k\text{th item}} \times \underbrace{\frac{v_k}{w_k}}_{\text{Profit per unit weight for } k\text{th item}}. \end{aligned}$$

# Promising Function

$$W = 16$$

$i$	$v_i$	$w_i$	$v_i/w_i$
1	\$40	2kg	20\$/kg
2	\$30	5kg	6\$/kg
3	\$50	10kg	5\$/kg
4	\$10	5kg	2\$/kg





# Pseudocode of the 0-1 Knapsack Problem

## Top level call

```
numbest = 0;
maxprofit = 0;
knapsack(0, 0, 0);
cout << maxprofit;
for (j = 1; j <= numbest; j++)
    cout << bestset[i];
```

```
void knapsack (index i, int profit, int weight)
{
    if (weight <= W && profit > maxprofit){
        maxprofit = profit;
        numbest = i;
        bestset = include;
    }

    if (promising(i)){
        include[i + 1] = "yes";
        knapsack(i + 1, profit + v[i + 1], weight + w[i + 1]);
        include[i + 1] = "no";
        knapsack(i + 1, profit, weight);
    }
}
```

```
bool promising (index i)
{
    index j, k;
    int totweight;
    float bound;

    if (weight >= W)
        return false;
    else{
        j = i + 1;
        bound = profit;
        totweight = weight;
        while (j <= n && totweight + w[j] <= W){
            totweight = totweight + w[j];
            bound = bound + v[j];
            j++;
        }
        k = j;
        if (k <= n)
            bound = bound + (W - totweight) * v[k] / w[k];
        return bound > maxprofit;
    }
}
```

# Conclusion

General process of developing a backtracking algorithm:

- Construct a state space tree.
- Design a promising function to stop at some nonpromising nodes and thus avoid full DFS over this state space tree.

# Conclusion

After this lecture, you should know:

- What is the difference between DFS and backtracking.
- What is a state space tree.
- What is a promising function.
- What kind of problems can be solved by backtracking.

# Thank you!

- Any question?
- Don't hesitate to send email to me for asking questions and discussion. 😊